Quadratic Quaternion Forms, Involutions and Triality

Max-Albert Knus and Oliver Villa

Received: May 31, 2001

Communicated by Ulf Rehmann

Abstract. Quadratic quaternion forms, introduced by Seip-Hornix (1965), are special cases of generalized quadratic forms over algebras with involutions. We apply the formalism of these generalized quadratic forms to give a characteristic free version of different results related to hermitian forms over quaternions:
1) An exact sequence of Lewis
2) Involutions of central simple algebras of exponent 2.
3) Triality for 4-dimensional quadratic quaternion forms.

1991 Mathematics Subject Classification: 11E39, 11E88
Keywords and Phrases: Quadratic quaternion forms, Involutions, Triality

1. Introduction

Let F be a field of characteristic not 2 and let D be a quaternion division algebra over F. It is known that a skew-hermitian form over D determines a symmetric bilinear form over any separable quadratic subfield of D and that the unitary group of the skew-hermitian form is the subgroup of the orthogonal group of the symmetric bilinear form consisting of elements which commute with a certain semilinear mapping (see for example Dieudonné [3]). Quadratic forms behave nicer than symmetric bilinear forms in characteristic 2 and Seip-Hornix developed in [9] a complete, characteristic-free theory of quadratic quaternion forms, their orthogonal groups and their classical invariants. Her theory was subsequently (and partly independently) generalized to forms over algebras (even rings) with involution (see [11], [10], [1], [8]).
Similitudes of hermitian (or skew-hermitian) forms induce involutions on the endomorphism algebra of the underlying space. To generalize the case where only similitudes of a quadratic form are considered, the notion of a quadratic pair was worked out in [6]. Relations between quadratic pairs and generalized quadratic forms were first discussed by Elomary [4].

The aim of this paper is to apply generalized quadratic forms to give a characteristic free presentation of some results on forms and involutions. After briefly recalling in Section 2 the notion of a generalized quadratic form (which, following the standard literature, we call an (ε,σ)-quadratic form) we give in Section 3 a characteristic-free version of an exact sequence of Lewis (see [7], [8, p. 389] and the appendix to [2]), which connects Witt groups of quadratic and quaternion algebras. The quadratic quaternion forms of Seip-Hornix are the main ingredient. Section 4 describes a canonical bijective correspondence between quadratic pairs and (ε,σ)-quadratic forms and Section 5 discusses the Clifford algebra. In particular we compare the definitions given in [10] and in [6]. In Section 6 we develop triality for 4-dimensional quadratic quaternion forms whose associated forms (over a separable quadratic subfield) are 3-Pfister forms. Any such quadratic quaternion form θ is an element in a triple $(\theta_1,\theta_2,\theta_3)$ of forms over 3 quaternions algebras D_1, D_2 and D_3 such that $[D_1][D_2][D_3]=1$ in the Brauer group of F. Triality acts as permutations on such triples.

2. Generalized quadratic forms

Let D be a division algebra over a field F with an involution $\sigma : x\mapsto \overline{x}$. Let V be a finite dimensional right vector space over D. An F-bilinear form

$$k : V\times V\to D$$

is *sesquilinear* if $k(xa,yb)=\overline{a}k(x,y)b$ for all x, $y\in V$, a, $b\in D$. The additive group of such maps will be denoted by $\operatorname{Sesq}_\sigma(V,D)$. For any $k\in\operatorname{Sesq}_\sigma(V,D)$ we write

$$k^*(x,y)=\overline{k(y,x)}.$$

Let $\varepsilon\in F^\times$ be such that $\varepsilon\overline{\varepsilon}=1$. A sesquilinear form k such that $k=\varepsilon k^*$ is called *ε-hermitian* and the set of such forms on V will be denoted by $\operatorname{Herm}^\varepsilon_\sigma(V,D)$. Elements of

$$\operatorname{Alt}^\varepsilon_\sigma(V,D)=\{g=f-\varepsilon f^* \mid f\in\operatorname{Sesq}_\sigma(V,D)\}.$$

are *ε-alternating forms.* We obviously have $\operatorname{Alt}^{-\varepsilon}_\sigma(V,D)\subset\operatorname{Herm}^\varepsilon_\sigma(V,D)$. We set

$$\mathrm{Q}^\varepsilon_\sigma(V,D)=\operatorname{Sesq}_\sigma(V,D)/\operatorname{Alt}^\varepsilon_\sigma(V,D)$$

and refer to elements of $\mathrm{Q}^\varepsilon_\sigma(V,D)$ as *(ε,σ)-quadratic forms.* We recall that (ε,σ)-quadratic forms were introduced by Tits [10], see also Wall [11], Bak [1] or Scharlau [8, Chapter 7]. For any algebra A with involution τ, let $\operatorname{Sym}^\varepsilon(A,\tau)=\{a\in A \mid a=\varepsilon\tau(a)\}$ and $\operatorname{Alt}^\varepsilon(A,\tau)=\{a\in A\mid a=c-\varepsilon\tau(c),\ c\in A\}$. To any class $\theta=[k]\in\mathrm{Q}^\varepsilon_\sigma(V,D)$, represented by $k\in\operatorname{Sesq}_\sigma(V,D)$, we associate a quadratic map

$$q_\theta : V\to D/\operatorname{Alt}^\varepsilon(D,\sigma),\quad q_\theta(x)=[k(x,x)]$$

where $[d]$ denotes the class of d in $D/\operatorname{Alt}^\varepsilon_\sigma(D)$. The ε-hermitian form

$$b_\theta(x,y)=k(x,y)+\varepsilon k^*(x,y)=k(x,y)+\varepsilon\overline{k(y,x)}$$

depends only on the class θ of k in $\mathrm{Q}^\varepsilon_\sigma(V,D)$. We say that b_θ is the *polarization* of q_θ.

Proposition 2.1. *The pair (q_θ, b_θ) satisfies the following formal properties:*

$$(1)\qquad \begin{array}{rcl} q_\theta(x+y) & = & q_\theta(x)+q_\theta(y)+[b_\theta(x,y)] \\ q_\theta(xd) & = & \overline{d}q_\theta(x)d \\ b_\theta(x,x) & = & q_\theta(x)+\varepsilon\overline{q_\theta(x)} \end{array}$$

for all $x,\ y\in V$, $d\in D$. Conversely, given any pair (q,b), $q: V\to D/\operatorname{Alt}^\varepsilon(D,\sigma)$, $b\in \operatorname{Herm}^\varepsilon_\sigma(V,D)$ satisfying (1)*, there exist a unique $\theta\in \mathrm{Q}^\varepsilon_\sigma(V,D)$ such that $q=q_\theta$, $b=b_\theta$.*

Proof. The formal properties are straightforward to verify. For the converse see [11, Theorem 1]. □

Example 2.2. Let $D=F$, $\sigma=Id_F$ and $\varepsilon=1$. Then sesquilinear forms are F-bilinear forms, $\operatorname{Alt}^\varepsilon(D,\sigma)=0$ and a (σ,ε)-quadratic form is a (classical) quadratic form. We denote the set of bilinear forms on V by $\operatorname{Bil}(V,F)$. Accordingly we speak of ε-symmetric bilinear forms instead of ε-hermitian forms.

Example 2.3. Let D be a division algebra with involution σ and let D be a finite dimensional (right) vector space over D. We use a basis of V to identify V with D^n and $\operatorname{End}_D(V)$ with the algebra $M_n(D)$ of $(n\times n)$-matrices with entries in D. For any $(n\times m)$-matrix $x=(x_{ij})$, let $x^*=\overline{x}^t$, where t is transpose and $\overline{x}=(\overline{x}_{ij})$. In particular the map $a\mapsto a^*$ is an involution of $A=M_n(D)$. If we write elements of D^n as column vectors $x=(x_1,\dots,x_n)^t$ any sesquilinear form k over D^n can be expressed as $k(x,y)=x^*ay$, with $a\in M_n(D)$, and $k^*(x,y)=x^*a^*y$. We write $\operatorname{Alt}_n(D)=\{a=b-\varepsilon b^*\}\subset M_n(D)$, so that $\mathrm{Q}^\varepsilon_\sigma(V,D)=M_n(D)/\operatorname{Alt}_n(D)$.

Example 2.4. Let D be a quaternion division algebra, i.e. D is a central division algebra of dimension 4 over F. Let K be a maximal subfield of D which is a quadratic Galois extension of F and let $\sigma: x\mapsto\overline{x}$ be the nontrivial automorphism of K. Let $j\in K\setminus F$ be an element of trace 1, so that $K=F(j)$ with $j^2=j+\lambda$, $\lambda\in F$. Let $\ell\in D$ be such that $\ell x\ell^{-1}=\overline{x}$ for $x\in K$, $\ell^2=\mu\in F^\times$. The elements $\{1,j,\ell,\ell j\}$ form a basis of D and $D=K\oplus\ell K$ is also denoted $[K,\mu)$. The F-linear map $\sigma: D\to D$, $\sigma(d)=\operatorname{Trd}_D(d)-d=\overline{d}$ is an involution of D (the "conjugation") which extends the automorphism σ of K. The element $\mathrm{N}(d)=d\sigma(d)=\sigma(d)d$ is the reduced norm of d. We have $\operatorname{Alt}^{-1}_\sigma(D)=F$ and $(\sigma,-1)$-quadratic forms correspond to the quadratic quaternion forms introduced by Seip-Hornix in [9]. Accordingly we call $(\sigma,-1)$-quadratic forms *quadratic quaternion forms*.

The restriction of the involution τ to the center Z of A is either the identity (*involutions of the first kind*) or an automorphism of order 2 (*involutions of the second kind*). If the characteristic of F is different from 2 or if the involution is of second kind there exists an element $j\in Z$ such that $j+\sigma(j)=1$. Under such conditions the theory of (σ,ε)-quadratic forms reduces to the theory of ε-hermitian forms:

PROPOSITION 2.5. *If the center of D contains an element j such that $j+\sigma(j) = 1$, then $\operatorname{Herm}_\sigma^{-\varepsilon}(V,D) = \operatorname{Alt}_\sigma^{\varepsilon}(V,D)$ and a (σ,ε)-quadratic form is uniquely determined by its polar form b_θ.*

Proof. If $k = -\varepsilon k^* \in \operatorname{Herm}_\sigma^{-\varepsilon}(V,D)$, then $k = 1k = jk + \overline{j}k = jk - \overline{j}\varepsilon k^* \in \operatorname{Alt}_\sigma^{\varepsilon}(V,D)$. The last claim follows from the fact that polarization induces an isomorphism $\operatorname{Sesq}_\sigma(V,D)/\operatorname{Herm}_\sigma^{-\varepsilon}(V,D) \xrightarrow{\sim} \mathrm{Q}_\sigma^{\varepsilon}(V,D)$. □

For any left (right) D-space V we denote by ${}^\sigma V$ the space V viewed as right (left) D-space through the involution σ. If ${}^\sigma x$ is the element x viewed as an element of ${}^\sigma V$, we have ${}^\sigma x d = {}^\sigma\big(\sigma(d)x\big)$. Let V^* be the dual ${}^\sigma\operatorname{Hom}_D(V,D)$ as a right D-module, i.e., $({}^\sigma f d)(x) = {}^\sigma(\overline{d}f)(x)$, $x \in V$, $d \in D$. Any sesquilinear form $k \in \operatorname{Sesq}_\sigma(V,D)$ induces a D-module homomorphism $\widehat{k} : V \to V^*$, $x \mapsto k(x,-)$. Conversely any homomorphism $g : V \to V^*$ induces a sesquilinear form $k \in \operatorname{Sesq}_\sigma(V,D)$, $k(x,y) = g(x)(y)$ and the additive groups $\operatorname{Sesq}_\sigma(V,D)$ and $\operatorname{Hom}_D(V,V^*)$ can be identified through the map $h \mapsto \widehat{k}$. For any $f : V \to V'$, let $f^* : V'^* \to V^*$ be the transpose, viewed as a homomorphisms of right vector spaces. We identify V with V^{**} through the map $v \mapsto v^{**}$, $v^{**}(f) = \overline{f(v)}$. Then, for any $f \in \operatorname{Hom}_D(V,V^*)$, f^* is again in $\operatorname{Hom}_D(V,V^*)$ and $\widehat{k}^* = \widehat{k^*}$. A (σ,ε)-quadratic form q_θ is called *nonsingular* if its polar form b_θ induces an isomorphism $\widehat{b_\theta}$. A pair (V,q_θ) with q_θ nonsingular is called a (σ,ε)-*quadratic space*. For any vector space W, the *hyperbolic space* $V = W \oplus W^*$ equipped with the quadratic form q_θ, $\theta = [k]$ with

$$k\big((p,q),(p',q')\big) = q(p'),$$

is nonsingular. There is an obvious notion of orthogonal sum $V \perp V'$ and a quadratic space decomposes whenever its polarization does. Most of the classical theory of quadratic spaces extends to (σ,ε)-quadratic spaces. For example Witt cancellation holds and any (σ,ε)-quadratic space decomposes uniquely (up to isomorphism) as the orthogonal sum of its anisotropic part with a hyperbolic space. Moreover, if we exclude the case $\sigma = 1$ and $\varepsilon = -1$, any (σ,ε)-quadratic space has an orthogonal basis. A *similitude* of (σ,ε)-quadratic spaces $t : (V,q) \xrightarrow{\sim} (V',q')$ is a D-linear isomorphism $V \xrightarrow{\sim} V'$ such that $q'(tx) = \mu(t)q(x)$ for some $\mu(t) \in F^\times$. The element $\mu(t)$ is called the *multiplier* of the similitude. Similitudes with multipliers equal to 1 are *isometries.* As in the classical case there is a notion of Witt equivalence and corresponding Witt groups are denoted by $W^\varepsilon(D,\sigma)$.

3. An exact sequence of Lewis

Let D be a quaternion division algebra. We fix a representation $D = [K,\mu) = K \oplus \ell K$, with $\ell^2 = \mu$, as in (2.4). Let V be a vector space over D. Any sesquilinear form $k : V \times V \to D$ can be decomposed as

$$k(x,y) = P(x,y) + \ell R(x,y)$$

with $P : V \times V \to K$ and $R : V \times V \to K$. The following properties of P and R are straightforward.

LEMMA 3.1. *1)* $P \in \mathrm{Sesq}_\sigma(V,K)$, $R \in \mathrm{Sesq}_1(V,K) = \mathrm{Bil}(V,K)$.
2) $k^* = P^* - \ell R^t$, *where* $P^*(x,y) = \overline{P(y,x)}$ *and* $R^t(x,y) = R(y,x)$.

The sesquilinearity of k implies the following identities:

$$(2)\qquad \begin{array}{rclrcl} R(x\ell,y) &=& -P(x,y), & R(x,y\ell) &=& \overline{P(x,y)} \\ P(x\ell,y) &=& -\mu R(x,y), & P(x,y\ell) &=& \mu\overline{R(x,y)} \\ P(x\ell,y\ell) &=& -\mu\overline{P(x,y)}, & R(x\ell,y\ell) &=& -\mu\overline{R(x,y)} \end{array}$$

Let V^0 be V considered as a (right) vector space over K (by restriction of scalars) and let $T : V^0 \to V^0, x \mapsto x\ell$. The map T is a K-semilinear automorphism of V^0 such that $T^2 = \mu$. Conversely, given a vector space U over K, together with a semilinear automorphism T such that $T^2 = \mu \in F^\times$, we define the structure of a right D-module on U, $D = [K,\mu)$, by putting $x\ell = T(x)$.

LEMMA 3.2. *Let* V *be a vector space over* D. *1) Let* $f_1 : V^0 \times V^0 \to K$ *be a sesquilinear form over* K. *The form*

$$f(x,y) = f_1(x,y) - \ell\mu^{-1} f_1(Tx,y)$$

is sesquilinear over D *if and only if* $f_1(Tx,Ty) = -\mu\overline{f_1(x,y)}$.
2) Let $f_2 : V^0 \times V^0 \to K$ *be a bilinear form over* K. *The form*

$$f(x,y) = -f_2(Tx,y) + \ell f_2(x,y)$$

is sesquilinear over D *if and only if* $f_2(Tx,Ty) = -\mu\overline{f_2(x,y)}$.

Proof. The two claims follow from the identities (2). □

Let f be a bilinear form on a space U over K and let $\lambda \in K^\times$. A semilinear automorphism t of U such that $f(tx,ty) = \lambda\overline{f(x,y)}$ for all $x \in U$ is a *semilinear similitude* of (U,f), with *multiplier* λ. In particular $Tx = x\ell$ is a semilinear similitude of R on V^0, such that $T^2 = \mu$ and with multiplier $-\mu$. The following nice observation of Seip-Hornix [9, p. 328] will be used later:

PROPOSITION 3.3. *Let* R *be a* K*-bilinear form over* U *and let* T *be a semilinear similitude of* U *with multiplier* $\lambda \in K^\times$ *and such that* $T^2 = \mu$. *Then:*
1) $\mu \in F$,
2) For any $\xi \in K$ *and* $x \in U$, *let* $\rho_\xi(x) = x\xi$. *There exists* $\nu \in K^\times$ *such that* $T' = \rho_\nu \circ T$ *satisfies* ${T'}^2 = \mu'$ *and* $R(T'x,T'y) = -\mu'\overline{R(x,y)}$.

Proof. The first claim follows from $\mu = \lambda\overline{\lambda}$. For the second we may assume that $\lambda \neq \mu$ (if $\lambda = \mu$ replace T by $T \circ \rho_k$ for an appropriate k). For $\nu = (1 - \mu\lambda^{-1})$ we have $\mu' = 2\mu - \lambda - \overline{\lambda}$. □

Assume that $k \in \mathrm{Sesq}_\sigma(V, D)$ defines a (σ, ε)-quadratic space $[k]$ on V over D. It follows from (3.1) that P defines a (σ, ε)-quadratic space $[P]$ on V^0 over K and R a $(Id, -\varepsilon)$-quadratic space $[R]$ on V^0 over K. Let $K = F(j)$ with $j^2 = j + \lambda$. Let $r(x, y) = R(x, y) - \varepsilon R(y, x)$ be the polar of R.

Proposition 3.4. *1)* $q_{[P]}(x) = \overline{\varepsilon} j[r(x, Tx)]$
2) $q_{[k]}(x) = \overline{\varepsilon} j[r(x, Tx)] + \ell q_{[R]}(x)$
3) The map T is a semilinear similitude of $\big(q_{[R]}, V^0\big)$ with multiplier $-\mu$.

Proof. It follows from the relations (2) that

$$\overline{P(x,x)} + \varepsilon P(x, x) = R(x, Tx) - \varepsilon R(Tx, x) = r(x, Tx) \tag{3}$$

and obviously this relation determines $P(x, x)$ up to a function with values in $\mathrm{Sym}^{-\varepsilon}(K, \sigma)$. Since $\mathrm{Sym}^{-\varepsilon}(K, \sigma) = \mathrm{Alt}^{+\varepsilon}(K, \sigma)$ by (2.5), $[P]$ is determined by (3). Since $\overline{r(x, Tx)} = \overline{\varepsilon} r(x, Tx)$ by (2), we have $\overline{\overline{\varepsilon} jr(x, Tx)} + \varepsilon\big(\overline{\varepsilon} jr(x, Tx)\big) = r(x, Tx)$ and 1) follows. The second claim follows from 1) and 3) is again a consequence of the identities (2). □

Corollary 3.5. *Any pair $\big([R], T\big)$ with $[R] \in \mathrm{Q}_1^\varepsilon(U, K)$ and T a semilinear similitude with multiplier $-\mu \in F^\times$ and such that $T^2 = \mu$, determines the structure of a (σ, ε)-quadratic space on U over $D = [K, \mu)$.*

Proposition 3.6. *The assignments $h \mapsto P$ and $h \mapsto R$ induce homomorphisms of groups $\pi_1 : W^\varepsilon(D, -) \to W^\varepsilon(K, -)$ and $\pi_2 : W^{-\varepsilon}(D, -) \to W^\varepsilon(K, Id)$.*

Proof. The assignments are obviously compatible with orthogonal sums and Witt equivalence. □

We recall that $W^\varepsilon(K, -)$ can be identified with the corresponding Witt group of ε-hermitian forms (apply (2.5)). However, it is more convenient for the following computations to view ε-hermitian forms over K as (σ, ε)- quadratic forms. Let $i \in K^\times$ be such that $\sigma(i) = -i$ (take $i = 1$ if $\mathrm{Char}\, F = 2$). The map $k \mapsto ik$ induces an isomorphism $s : W^\varepsilon(K, -) \xrightarrow{\sim} W^{-\varepsilon}(K, -)$ ("scaling"). For any space U over K, let $U_D = U \otimes_K D$. We identify U_D with $U \oplus U\ell$ through the map $u \otimes (x + \ell y) \mapsto (ux, u\overline{y}l)$ and get a natural D-module structure on $U_D = U \oplus U\ell$. Any K-sesquilinear form k on U extends to a D-sesquilinear form k_D on U_D through the formula

$$k_D(x \otimes a, y \otimes b) = \overline{a} k(x, y) b$$

for x, $y \in U$ and a, $b \in D$.

Lemma 3.7. *The assignment $k \mapsto (ik)_D$ induces a homomorphism*

$$\beta : W^\varepsilon(K, -) \to W^{-\varepsilon}(D, -)$$

Proof. Let $\widetilde{k} = (ik)_D$. We have $(\widetilde{k})^* = -\widetilde{k^*}$. □

Theorem 3.8 (Lewis). *With the notations above, the sequence*

$$W^\varepsilon(D,-) \xrightarrow{\pi_1} W^\varepsilon(K,-) \xrightarrow{\beta} W^{-\varepsilon}(D,-) \xrightarrow{\pi_2} W^\varepsilon(K,Id)$$

is exact.

Proof. This is essentially the proof given in Appendix 2 of [2] with some changes due to the use of generalized quadratic forms, instead of hermitian forms. We first check that the sequence is a complex. Let $[k]\in \mathrm{Q}^\varepsilon_\sigma(V,D)$ and let $V^0=U$. We write elements of $U_D=U\oplus U\ell$ as pairs $(x,y\ell)$ and decompose $k_D=P+\ell R$. By definition we have $\beta\pi_1([k])=[\beta(P)]$ and

$$\begin{aligned}\beta(P)\big((x_1,y_1),(x_2,y_2)\big) &= i\big(P(x_1,x_2)+P(x_1,y_2)\ell+\ell P(y_1,x_2)\\ &\quad +\ell P(y_1,y_2)\ell\big).\end{aligned}$$

Let $(x\ell,x\ell)\in U\oplus U\ell$. We get $\beta(P)\big((x\ell,x\ell),(x\ell,x\ell)\big)=0$ hence $W=\{(x\ell,x\ell)\}\subset U\oplus U\ell$ is totally isotropic. It is easy to see that $W\subset W^\perp$, so that $[\beta(P)]$ is hyperbolic and $\beta\circ\pi_1=0$. Let $[g]\in \mathrm{Q}^\varepsilon_\sigma(U,K)$. The subspace $W=\{(x,0)\in U\oplus U\ell\}$ is totally isotropic for $\pi_2\beta([g])$ and $W\subset W^\perp$. Hence $\pi_2\beta([g])=0$. We now prove exactness at $W^\varepsilon(K,-)$. Since the claim is known if Char $\neq 2$, we may assume that Char $=2$ and $\varepsilon=1$. Let $[g]\in \mathrm{Q}^\varepsilon_\sigma(U,K)$ be anisotropic such that $\beta([g])=0\in W^{-\varepsilon}(D,-)$. In particular $\beta([g])\in \mathrm{Q}^{-\varepsilon}_\sigma(U_D,D)$ is isotropic. Hence the exist elements $x_1,\ x_2\in U$ such that $[\widetilde{g}]\big((x_1,x_2\ell),(x_1,x_2\ell)\big)=0$. This implies (in Char 2) that

$$g(x_1,x_1)+\mu\overline{g(x_2,x_2)}\in F,\quad g(x_1,x_2)\ell+\ell g(x_2,x_1)=0. \tag{4}$$

Let V_1 be the K-subspace of V generated by x_1 and x_2. Since $[g]$ is anisotropic, $[g]=[g_1]\perp[g_2]$ with $g_1=g|_{V_1}$. We make V_1 into a D-space by putting

$$(x_1a_1+x_2a_2)\ell=\mu x_2\overline{a}_1+x_1\overline{a}_2$$

To see that the action is well-defined, it suffices to show that $\dim_K V_1=2$. The elements x_1 and x_2 cannot be zero since $[g]$ is anisotropic, so assume $x_2=x_1c,\ c\in K^\times$. Then (4) implies $g(x_1,x_1)+\mu c\overline{c}\overline{g(x_1,x_1)}\in F$, which contradicts the fact that g is anisotropic. Let $g_1(x_1,x_1)+\mu\overline{g_1(x_2,x_2)}=z\in F$. Let $f\in \mathrm{Sesq}_\sigma(V_1,K)$. Replacing g_1 by g_1+f+f^* defines the same class in $\mathrm{Q}^\varepsilon_\sigma(V_1,K)$ (recall that Char $F=2$). Choosing f as

$$f(x_1,x_1)=jz,\ f(x_2,x_2)=0,\ f(x_1,x_2)=f(x_2,x_1)=0,$$

we may assume that

$$g_1(x_1,x_1)+\mu\overline{g_1(x_2,x_2)}=0,\quad g_1(x_1,x_2)\ell+\ell g_1(x_2,x_1)=0. \tag{5}$$

By (3.2) we may extend g_1 to a sesquilinear form

$$g'(x,y)=g_1(x,y)+\ell\mu^{-1}g_1(x\ell,y)$$

over D if g_1 satisfies

$$g_1(x\ell,y\ell)=-\mu\overline{g_1(x,y)}$$

This can easily be checked using (5) (and the definition of $x\ell$). Then g_1 is in the image of π_1. Exactness at $W^\varepsilon(K,-)$ now follows by induction on the dimension of U. We finally check exactness at $W^{-\varepsilon}(D,-)$. Let $[k]$ be anisotropic such that $\pi_2([k]) = 0$ in $W^{-\varepsilon}(K, Id)$. In particular $\pi_2([k])$ is isotropic; let $x \neq 0$ be such that $\pi_2 k(x,x) = 0$ and let W be the D-subspace of V generated by x. Since $[k]$ is anisotropic, $[k'] = [k|_W]$ is nonsingular and $[k] = [k'] \perp [k'']$. The condition $\pi_2 k(x,x) = 0$ implies $k(x,x) \in K$. Let W_1 be the K-subspace of W generated by x. Define $g : W_1 \times W_1 \to K$ by $g(xa, xb) = k(xa, xb)i^{-1}$ for a, $b \in K$. Then clearly $[g]$ defines an element of $W^{\varepsilon}(K,-)$ and $\beta(g) = k'$. Once again exactness follows by induction on the dimension of V. □

4. Involutions on central simple algebras

Let D be a central division algebra over F, with involution σ and let $b : V \times V \to D$ be a nonsingular ε-hermitian form on a finite dimensional space over D. Let $A = \mathrm{End}_D(V)$. The map $\sigma_b : A \to A$ such that $\sigma_b(\lambda) = \sigma(\lambda)$ for all $\lambda \in F$ and

$$b\big(\sigma_b(f)(x), y\big) = b\big(x, f(y)\big)$$

for all x, $y \in V$, is an involution of A, called the involution *adjoint to* b. We have $\sigma_b(f) = \widehat{b}^{-1} f^* \widehat{b}$, where $\widehat{b} : V \xrightarrow{\sim} V^*$ is the adjoint of b. Conversely, any involution of A is adjoint to some nonsingular ε-hermitian form b and b is uniquely multiplicatively determined up to a σ-invariant element of $F^{\times}$.
Any automorphism ϕ of A compatible with σ_b, i.e., $\sigma_b\big(\phi(a)\big) = \phi\big(\sigma_b(a)\big)$, is of the form $\phi(a) = uau^{-1}$ with $u : V \xrightarrow{\sim} V$ a similitude of b. We say that an involution τ of A is a *q-involution* if τ is adjoint to the polar b_θ of a (σ, ε)-quadratic form θ. We write $\tau = \sigma_\theta$. Two algebras with q-involutions are *isomorphic* if the isomorphism is induced by a similitude of the corresponding quadratic forms. Over fields q-involutions differ from involutions only in characteristic 2 and for symplectic involutions. In view of possible generalizations (for example rings in which $2 \neq 0$ is not invertible) we keep to the general setting of (σ, ε)-quadratic forms. Let F_0 be the subfield of F of σ-invariant elements and let T_{F/F_0} be the corresponding trace.

LEMMA 4.1. *The symmetric bilinear form on* A *given by* $\mathrm{Tr}(x,y) = T_{F/F_0}\big(\mathrm{Trd}_A(xy)\big)$ *is nonsingular and* $\mathrm{Sym}(A,\tau)^{\perp} = \mathrm{Alt}(A,\tau)$.

Proof. If τ is of the first kind $F_0 = F$ and the claim is (2.3) of [6]. Assume that τ is of the second kind. Since the bilinear form $(x,y) \to \mathrm{Trd}_A(xy)$ is nonsingular, Tr is also nonsingular and it is straightforward that $\mathrm{Alt}(A,\tau) \subset \mathrm{Sym}(A,\tau)^{\perp}$. Equality follows from the fact that $\dim_{F_0} \mathrm{Alt}(A,\tau) = \dim_{F_0} \mathrm{Sym}(A,\tau) = \dim_F A$. □

PROPOSITION 4.2. *Let* (V,θ), $\theta = [k]$ *be a* (σ,ε)*-quadratic space over* D *and let* $h = \widehat{k} + \varepsilon \widehat{k}^* : V \xrightarrow{\sim} V^*$. *The* F_0*-linear form*

$$f_\theta : \mathrm{Sym}(A, \sigma_\theta) \to F_0, \quad f_\theta(s) = \mathrm{Tr}(h^{-1}\widehat{k}s), \ s \in \mathrm{Sym}(A, \sigma_\theta)$$

depends only on the class θ *and satisfies* $f_\theta\big(x + \sigma_\theta(x)\big) = \mathrm{Tr}(x)$.

Proof. The first claim follows from (4.1) and the fact that if $k \in \mathrm{Alt}^{\varepsilon}_{\sigma}(V,D)$ then $h^{-1}\widehat{k} \in \mathrm{Alt}^{1}_{\sigma_\theta}(V,D)$. For the last claim we have:

$$\begin{aligned} f_\theta\big(x+\sigma_\theta(x)\big) &= \mathrm{Tr}\big(h^{-1}\widehat{k}(x+\sigma_\theta(x)\big) \\ &= \mathrm{Tr}\big(h^{-1}\widehat{k}x\big) + \mathrm{Tr}\big(h^{-1}\widehat{k}h^{-1}x^*h\big) \\ &= \mathrm{Tr}\big(h^{-1}\widehat{k}x\big) + \mathrm{Tr}\big(\widehat{k}h^{-1}x^*\big) \\ &= \mathrm{Tr}\big(h^{-1}\widehat{k}x\big) + \mathrm{Tr}\big(x(h^{-1})^*\widehat{k}^*\big) \\ &= \mathrm{Tr}\big(h^{-1}\widehat{k}x\big) + \mathrm{Tr}\big(h^{-1}\varepsilon\widehat{k}^*x\big) = \mathrm{Tr}(x). \end{aligned}$$

□

LEMMA 4.3. *Let τ be an involution of $A = \mathrm{End}_D(V)$ and let f be A F_0-linear form on $\mathrm{Sym}(A,\tau)$ such that $f\big(x+\tau(x)\big) = \mathrm{Tr}(x)$ for all $x \in A$. There exists an element $u \in A$ such that $f(s) = \mathrm{Tr}(us)$ and $u + \tau(u) = 1$. The element u is uniquely determined up to additivity by an element of $\mathrm{Alt}(A,\tau)$. We take $u = 1/2$ if $\mathrm{Char}\, F \neq 2$.*

Proof. The proof of (5.7) of [6] can easily be adapted. □

PROPOSITION 4.4. *Let τ be an involution of $A = \mathrm{End}_D(V)$ and let f be A F_0-linear form on $\mathrm{Sym}(A,\tau)$ such that $f\big(x+\tau(x)\big) = \mathrm{Tr}(x)$ for all $x \in A$.*
1) There exists a nonsingular (σ,ε)-quadratic form θ on V such that $\tau = \sigma_\theta$ and $f = f_\theta$.
2) $(\sigma_\theta, f_\theta) = (\sigma_{\theta'}, f_{\theta'})$ if and only if $\theta' = \lambda\theta$ for $\lambda \in F_0$.
3) If $\tau = \sigma_\theta$ and $f = f_\theta$ with $f_\theta(s) = \mathrm{Tr}(us)$, the class of u in $A/\mathrm{Alt}(A,\sigma_\theta)$ is uniquely determined by θ.

Proof. Here the proof of (5.8) of [6] can adapted. We prove 1) for completeness. Let $\tau(x) = h^{-1}x^*h$, $h = \varepsilon h^* : V \xrightarrow{\sim} V^*$. Let $f(s) = \mathrm{Tr}(us)$ with $u + \tau(u) = 1$ and let $k \in \mathrm{Sesq}_\sigma(V,D)$ be such that $\widehat{k} = hu : V \to V^*$. We set $\theta = [k]$. It is then straightforward to check that $h = k + \varepsilon k^*$. □

PROPOSITION 4.5. *Let $\phi : \big(\mathrm{End}_D(V), \sigma_\theta\big) \xrightarrow{\sim} \big(\mathrm{End}_D(V'), \sigma_{\theta'}\big)$ be an isomorphism of algebras with involution. Let $f_\theta(s) = \mathrm{Tr}(us)$ and $f_{\theta'}(s') = \mathrm{Tr}(u's')$. The following conditions are equivalent:*
1) ϕ is an isomorphism of algebras with q-involutions.
2) $f_{\theta'}\big(\phi(s)\big) = f_\theta(s)$ for all $s \in \mathrm{Sym}\big(\mathrm{End}_D(V), \sigma_\theta\big)$.
3) $[\phi(u)] = [u'] \in \mathrm{End}_D(V')/\mathrm{Alt}\big(\mathrm{End}_D(V'), \sigma_{\theta'}\big)$.

Proof. The implication 1) ⇒ 2) is clear. We check that 2) ⇒ 3). Let ϕ be induced by a similitude $t : (V, b_\theta) \xrightarrow{\sim} (V', b_{\theta'})$. Since $f_{\theta'}(\phi s) = f_\theta(s)$, we have $\mathrm{Tr}(t^{-1}u'ts) = \mathrm{Tr}(u'tst^{-1}) = \mathrm{Tr}(us)$ for all $s \in \mathrm{Sym}\big(\mathrm{End}_D(V), \sigma_\theta\big)$, hence $[\phi(u)] = [u']$. The implication 3) ⇒ 1) follows from the fact that u can be chosen as $h^{-1}\widehat{k}$, $h = \widehat{k} + \varepsilon\widehat{k}^*$. □

Remark 4.6. We call the pair $(\sigma_\theta, f_\theta)$ a (σ,ε)-*quadratic pair* or simply a quadratic pair. It determines θ up to the multiplication by a σ-invariant scalar $\lambda \in F^\times$. In fact σ_θ determines the polar b_θ up to λ and f_θ determines u. We have $\theta = [\widehat{b_\theta} u]$.

Example 4.7. Let $q : V \to F$ be a nonsingular quadratic form. The polar b_q induces an isomorphism $\psi : V \otimes_F V \xrightarrow{\sim} \operatorname{End}_F(V)$ such that $\sigma_q\big(\psi(x\otimes y)\big) = \psi(y \otimes x)$. Thus $\psi(x\otimes x)$ is symmetric and $f_q\big(\psi(x\otimes x)\big) = q(x)$ (see [6, (5.11)]. More generally, if V is a right vector space over D, we denote by ${}^*V$ the space V viewed as a left D-space through the involution σ of D. The adjoint $\widehat{b_\theta}$ of a (σ,ε)-quadratic space (V,θ) induces an isomorphism $\psi_\theta : V \otimes_D {}^\sigma V \xrightarrow{\sim} \operatorname{End}_D(V)$ and $\psi_\theta(xd\otimes x)$ is a symmetric element of $\big(\operatorname{End}_D(V), \sigma_\theta\big)$ for all $x \in V$ and all ε-symmetric $d \in D$. One has $f_\theta\big(\psi(xd\otimes x)\big) = [dk(x,x)]$, where $\theta = [k]$ (see [4, Theorem 7]).

5. Clifford algebras

Let σ be an involution of the first kind on D and let θ be a nonsingular (σ,ε)-quadratic form on V. Let σ_θ be the corresponding q-involution on $A = \operatorname{End}_D(V)$. We assume in this section that over a splitting $A \otimes_F \tilde{F} \xrightarrow{\sim} \operatorname{End}_{\tilde{F}}(M)$ of A, $\theta_{\tilde{F}} = \theta \otimes 1_{\tilde{F}}$ is a $(Id, 1)$-quadratic form $\tilde{q}$ over $\tilde{F}$, i.e. $\theta_{\tilde{F}}$ is a (classical) quadratic form. In the terminology of [6] this means that σ_θ is orthogonal if Char $\neq 2$ and symplectic if Char $= 2$. From now on we call such forms over D *quadratic forms over* D, resp. *quadratic spaces* over D if the forms are non-singular.

Classical invariants of quadratic spaces (V,θ) are the dimension $\dim_D V$ and the discriminant $\operatorname{disc}(\theta)$ and the Clifford invariant associated with the Clifford algebra. We refer to [6, §7] for the definition of the discriminant. We recall the definition of the Clifford algebra $\operatorname{Cl}(V,\theta)$, following [10, 4.1]. Given (V,θ) as above, let $\theta = [k]$, $k \in \operatorname{Sesq}_\sigma(V,D)$, $b_\theta = k + \varepsilon k^*$ and $h = \widehat{b_\theta} \in \operatorname{Hom}_D(V, V^*)$. Let $A = \operatorname{End}_D(V)$, $B = \operatorname{Sesq}_\sigma(V,D)$ and $B' = V \otimes_D {}^\sigma V$. We identify A with $V \otimes_D {}^\sigma V^*$ through the canonical isomorphism $(x \otimes {}^\sigma f)(v) = xf(v)$ and B with $V^* \otimes_D {}^\sigma V^*$ through $(f \otimes {}^\sigma g)(x,y) = \overline{g(x)} f(y)$. The isomorphism h can be used to define further isomorphisms:

$$\varphi_\theta : B' = V \otimes_D {}^\sigma V \xrightarrow{\sim} A = \operatorname{End}_D(M),\ \varphi_\theta : x\otimes y \mapsto x \otimes h(y)$$

and the isomorphism ψ_θ already considered in (4.7):

$$\psi_\theta : A \xrightarrow{\sim} B,\ \psi_\theta : x \otimes {}^\sigma f \mapsto h(x) \otimes {}^\sigma f.$$

We use φ_θ and ψ_θ to define maps $B' \times B \to A$, $(b', b) \mapsto b'b$ and $A \times B' \to B'$, $(a, b') \mapsto ab'$:

$$(x \otimes {}^\sigma y)(h(u) \otimes g) = xb(y,u) \otimes {}^\sigma f \text{ and } (x\otimes, {}^\sigma f)(u\otimes, {}^\sigma v) = xf(u) \otimes {}^\sigma h(v)$$

Furthermore, let $\tau_\theta = \varphi_\theta^{-1}\sigma_\theta\varphi_\theta : B' \to B'$ be the transport of the involution σ_θ on A. We have $\tau_\theta(x \otimes {}^\sigma y) = \varepsilon y \otimes {}^\sigma x$. Let $S_1 = \{s_1 \in B' \mid \tau_\theta(s_1) = s_1\}$. We have $S_1 = \big(\mathrm{Alt}^\varepsilon(V,D)\big)^\perp$ for the pairing $B' \times B \to F$, $(b',b) \mapsto \mathrm{Trd}_A(b'b)$. Let Sand be the bilinear map $B' \otimes B' \times B \to B'$ defined by $\mathrm{Sand}(b'_1 \otimes b'_2, b) = b'_2 b b'_1$. The *Clifford algebra* $\mathrm{Cl}(V,\theta)$ of the quadratic space (V,θ) is the quotient of the tensor algebra of the F-module B' by the ideal I generated by the sets

$$\begin{array}{rcl} I_1 & = & \{s_1 - \mathrm{Trd}_A(s_1 k)1,\ s_1 \in S_1\} \\ I_2 & = & \{c - \mathrm{Sand}(c,k) \mid \mathrm{Sand}\big(c, \mathrm{Alt}^\varepsilon(V,D)\big) = 0\}. \end{array}$$

The Clifford algebra $\mathrm{Cl}(V,\theta)$ has a canonical involution σ_0 induced by the map τ. We have $\mathrm{Cl}(V,\theta) \otimes_F \widetilde{F} = \mathrm{Cl}(V \otimes_F \widetilde{F}, \theta \otimes 1_{\widetilde{F}})$ for any field extension $\widetilde{F}$ of F and $\mathrm{Cl}(V,q)$ is the even Clifford algebra $C_0(V,q)$ of (V,q) if $D = F$ ([10, Théorème 2]). The reduction is through Morita theory for hermitian spaces (see for example [5, Chapter I, §9] for a description of Morita theory). In [6, §8] the Clifford algebra $C(A,\sigma_\theta,f_\theta)$ of the triple $(A,\sigma_\theta,f_\theta)$ is defined as the quotient of the tensor algebra $T(A)$ of the F-space A by the ideal generated by the sets

$$\begin{array}{rcl} J_1 & = & \{s - \mathrm{Trd}_A(us),\ s \in \mathrm{Sym}(A,\sigma_\theta)\} \\ J_2 & = & \{c - \mathrm{Sand}'(c,u),\ c \in A \text{ with } \mathrm{Sand}'\big(c, \mathrm{Alt}(A,\sigma_\theta)\big) = 0\} \end{array}$$

where $u = \widehat{b_\theta}^{-1} k$ and $\mathrm{Sand}' : (A \otimes A, A) \to A$ is defined as $\mathrm{Sand}'(a \otimes b, x) = axb$. The two definitions give in fact isomorphic algebras:

Proposition 5.1. *The isomorphism $\varphi_\theta : V \otimes_D {}^\sigma V \xrightarrow{\sim} \mathrm{End}_D(V)$ induces an isomorphism $\mathrm{Cl}(V,\theta) \xrightarrow{\sim} C(A,\sigma_\theta,f_\theta)$.*

Proof. We only check that φ_θ maps I_1 to J_1. By definition of τ and S_1, $s = \varphi_\theta(s_1)$ is a symmetric element of A. On the other hand we have by definition of the pairing $B' \times B \to A$,

$$\begin{array}{rcl} \mathrm{Trd}_A(s_1 k) & = & \mathrm{Trd}_A\big(\varphi_\theta(s_1)\psi_\theta^{-1}(k)\big) \\ & = & \mathrm{Trd}_A\big(sh^{-1}\widehat{k}\big) = \mathrm{Trd}_A(su) = \mathrm{Trd}_A(us), \end{array}$$

hence the claim. □

In particular we have $C\big(\mathrm{End}_F(V), \sigma_q, f_q\big) = C_0(V,q)$ for a quadratic space (V,q) over F. It is convenient to use both definitions of the Clifford algebra of a generalized quadratic space.

Let $D = [K,\mu) = K \oplus \ell K$ be a quaternion algebra with conjugation σ. Let V be a D-module and let V^0 be V as a right vector space over K (through restriction of scalars). Let $T : V^0 \to V^0$, $Tx = x\ell$. We have $\mathrm{End}_D(V) \subset \mathrm{End}_K(V^0)$ and

$$\mathrm{End}_D(V) = \{f \in \mathrm{End}_K(V^0) \mid fT = Tf\}.$$

Let $\theta = [k]$ be a $(\sigma,-1)$-quadratic space and let $k(x,y) = P(x,y) + \ell R(x,y)$ as in Section 3. It follows from (3.1) that R defines a quadratic space $[R]$ on V^0 over K.

Proposition 5.2. *We have $\sigma_{[R]}|_{\mathrm{End}_D(V)} = \sigma_\theta$ and $f_\theta = f_{[R]}|_{\mathrm{End}_D(V)}$.*

Proof. We have an embedding $D \hookrightarrow M_2(K)$, $a + \ell b \mapsto \begin{pmatrix} a & \mu\bar{b} \\ b & \bar{a} \end{pmatrix}$ and conjugation given by $x \mapsto x^* = c^{-1}x^t c$, $c = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$. The choice of a basis of V over D identifies V with D^n, V^0 with K^{2n}, $\mathrm{End}_D(V)$ with $M_n(D)$ and $\mathrm{End}_K(V^0)$ with $M_{2n}(K)$, where $n = \dim_D V$. We further identify V and V^* through the choice of the dual basis. We embed any element $x = x_1 + \ell x_2 \in M_{k,l}(D)$, $x_i \in M_{k,l}(K)$ in $M_{2k,2l}(K)$ through the map $\iota : x \mapsto \xi = \begin{pmatrix} x_1 & \mu\overline{x_2} \\ x_2 & \overline{x_1} \end{pmatrix}$. In particular D^n is identified with a subspace of the space of $(2n \times 2)$-matrices over K. Then $D \subset M_2(K)$ operates on the right through (2×2)-matrices and $M_n(D) \subset M_{2n}(K)$ operates on the left through $(2n \times 2n)$-matrices. With the notations of Example (2.3) we have $\iota(x^*) = \mathrm{Int}(c^{-1})(x^t)$. Any D-sesquilinear form k on D^n can be written as $k(x, y) = x^*ay$, where $a \in M_n(D)$, as in (2.3). Let $a = a_1 + \ell a_2$, $a_i \in M_n(K)$ and let

$$\alpha = \iota(a) = \begin{pmatrix} a_1 & \mu\overline{a_2} \\ a_2 & \overline{a_1} \end{pmatrix}.$$

Let $\eta = \iota(y)$, $y = y_1 + \ell y_2$. We have

$$k(x, y) = x^*ay = \xi^*\alpha\eta = \begin{pmatrix} x_1 & \mu\overline{x_2} \\ x_2 & \overline{x_1} \end{pmatrix}^* \begin{pmatrix} a_1 & \mu\overline{a_2} \\ a_2 & \overline{a_1} \end{pmatrix} \begin{pmatrix} y_1 & \mu\overline{y_2} \\ y_2 & \overline{y_1} \end{pmatrix}.$$

On the other side it follows from $h = P + \ell R$ that $R(x, y) = \xi^t\rho\eta$ with

$$\rho = \begin{pmatrix} a_2 & \overline{a_1} \\ -a_1 & -\mu\overline{a_2} \end{pmatrix}.$$

Assume that $\theta = [k]$, so that σ_θ corresponds to the involution $\mathrm{Int}(\gamma^{-1}) \circ *$, where $\gamma = \alpha - \alpha^*$. Similarly $\sigma_{[R]}$ corresponds to the involution $\mathrm{Int}(\widetilde{\rho}^{-1}) \circ t$ where $\widetilde{\rho} = \rho + \rho^t$. We obviously have $\rho = c\alpha$ with $c = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$, so that $\rho^t = \alpha^t c^t = -\alpha^t c = -ca^*$ and $\rho + \rho^t = c(\alpha - \alpha^*)$ or $c\gamma = \widetilde{\rho}$. Now $^* = \mathrm{Int}(c^{-1}) \circ t$ implies $\sigma_{[R]}|_{M_n(D)} = \sigma_\theta$. We finally check that $f_\theta = f_{[R]}|_{\mathrm{Sym}(M_n(D),\sigma_\theta)}$. We have $f_\theta(s) = \mathrm{Trd}_{M_n(D)}(\gamma^{-1}\alpha s)$ and $f_{[R]}(s) = \mathrm{Trd}_{M_{2n}(K)}(\widetilde{\rho}^{-1}\rho s)$, hence the claim, since $\rho = c\alpha$ and $\widetilde{\rho} = c\gamma$ implies $\gamma^{-1}\alpha = \widetilde{\rho}^{-1}\rho$. □

COROLLARY 5.3. *The embedding* $\mathrm{End}_D(V) \hookrightarrow \mathrm{End}_K(V^0)$ *induces*
1) an isomorphism $\big(\mathrm{End}_D(V), \sigma_\theta, f_\theta\big) \otimes K \xrightarrow{\sim} \big(\mathrm{End}_K(V^0), \sigma_{[R]}, f_{[R]}\big)$,
2) an isomorphism $C\big(\mathrm{End}_D(V), \sigma_\theta, f_\theta\big) \otimes K \xrightarrow{\sim} C_0(V^0, [R])$.

In view of (2) the semilinear automorphism $T : V^0 \xrightarrow{\sim} V^0$, $Tx = x\ell$, is a semilinear similitude with multiplier $-\mu$ of the quadratic form $[R]$, such that $T^2 = \mu$.

LEMMA 5.4. *The map T induces a semilinear automorphism $C_0(T)$ of $C_0(V^0, R)$ such that*

$$C_0(T)(xy) = (-\mu)^{-1}T(x)T(y) \text{ for } x,\, y \in V^0$$

and $C_0(T)^2 = Id$.

Proof. This follows (for example) as in [6, (13.1)] □

Proposition 5.5.

$$C\big(\mathrm{End}_D(V), \sigma_\theta, f_\theta\big) = \{c \in C_0(V^0, R) \mid C_0(T)(c) = c\}.$$

Proof. The claim follows from the defining relations of $C\big(\mathrm{End}_D(V), \sigma_\theta, f_\theta\big)$ and the fact that

$$\mathrm{End}_D(V) = \{f \in \mathrm{End}_K(V^0) \mid T^{-1} f T = f\}.$$

□

We call $C\big(\mathrm{End}_D(V), \sigma_\theta, f_\theta\big)$ or equivalently $\mathrm{Cl}(V, \theta)$ the *Clifford algebra of the quadratic quaternion space* (V, θ).

Let t be a semilinear similitude of a quadratic space (U, q) of even dimension over K. Assume that $\mathrm{disc}(q)$ is trivial, so that $C_0(U, q)$ decomposes as product of two K-algebras $C^+(U, q)$ and $C^-(U, q)$. We say that t is *proper* if $C_0(t)\big(C^\pm(U, q)\big) \subset C^\pm(U, q)$ and we say that t is *improper* if $C_0(t)\big(C^\pm(U, q)\big) \subset C^\mp(U, q)$. In general we say that t is *proper* if t is proper over some field extension of F which trivializes $\mathrm{disc}(q)$. For any semilinear similitude t, let $d(t) = 1$ is t if proper and $d(t) = -1$ if t is improper.

Lemma 5.6. *Let t_i be a semilinear similitude of (U_i, q_i), $i = 1, 2$. We have $d(t_1 \perp t_2) = d(t_1)d(t_2)$.*

Proof. We assume that $\mathrm{disc}(q_i)$, $i = 1, 2$, is trivial. Let e_i be an idempotent generating the center Z_i of $C_0(q_i)$. We have $t_i(e_i) = e_i$ if t_i is proper and $t_i(e_i) = 1 - e_i$ if t_i is improper. The idempotent $e = e_1 + e_2 - 2e_1e_2 \in C_0(q_1 \perp q_2)$ generates the center of $C_0(q_1 \perp q_2)$ (see for example [5, (2.3), Chap. IV]) and the claim follows by case checking. □

Lemma 5.7. *Let V, θ, V^0, R and T be as above. Let $\dim_K V^0 = 2m$. Then T is proper if m is even and is improper if m is odd.*

Proof. The quadratic space (V, θ) is the orthogonal sum of 1-dimensional spaces and we get a corresponding orthogonal decomposition of $\big(V^0, [R]\big)$ into subspaces (U_i, q_i) of dimension 2. In view of (5.6) it suffices to check the case $m = 1$. Let $\alpha = a = a_1 + \ell a_2 \in D$ and $\rho = \begin{pmatrix} a_2 & \overline{a_1} \\ -a_1 & -\mu\overline{a_2} \end{pmatrix}$. We choose $\mu = 1$, $a_1 = j$ (j as in (2.4)), put $i = 1 - 2j$, so that $\bar{i} = -i$ and choose $a_2 = 0$. Let $x = x_1e_1 + x_2e_2 \in V^0$, so $[R](x_1, x_2) = ix_1x_2$ and $C([R])$ is generated by e_1, e_2 with the relations $e_1^2 = 0$, $e_2^2 = 0$, $e_1e_2 + e_2e_1 = i$. The element $e = i^{-1}e_1e_2$ is an idempotent generating the center. Since $T(x_1e_1 + x_2e_2) = \overline{x}_2e_1 + \overline{x}_1e_2$, we have $C_0(T)(e_1e_2) = -e_2e_1$ and $C_0(T)(e) = 1 - e$. Thus T is not proper. □

Of special interest for the next section are quadratic quaternion forms $[k]$ such that the induced quadratic forms $\pi_2([k])$ are Pfister forms. For convenience we call such forms *Pfister quadratic quaternion forms*. Hyperbolic spaces of dimension 2^n are Pfister forms, hence spaces of the form $\beta([b])$, b a hermitian form over K, are Pfister, in view of the exactness of the sequence of Lewis [7]. It is in fact easy to give explicit examples of Pfister forms using the following constructions:

EXAMPLE 5.8 ($\operatorname{Char} F \neq 2$). Let $q =< \lambda_1, \dots, \lambda_n >$ be a diagonal quadratic form on F^n, i.e., $q(x) = \sum \lambda_i x_i^2$. Let $[k]$ on D^n be given by the diagonal form ℓq. Then the corresponding quadratic form $[R]$ on K^{2n} is given by the diagonal form $< 1, -\mu > \otimes q$. In particular we get the 3-Pfister form $<< a, b, \mu >>$ choosing for q the norm form of a quaternion algebra $(a, b)_F$.

EXAMPLE 5.9 ($\operatorname{Char} F = 2$). Let $b =< \lambda_1, \dots, \lambda_n >$ be a bilinear diagonal form on F^n, i.e., $b(x, y) = \sum \lambda_i x_i y_i$. Let $k = (j + \ell)b$ on D^n. Then the corresponding quadratic form $[R]$ over $K = R(j)$, $j^2 = j + \lambda$, is given by the form $[R] = b \otimes [1, \lambda]$ where $[\xi, \eta] = \xi x_1^2 + x_1 x_2 + \eta {x_2}^2$. In particular, for $b =< 1, a, c, ac >$, we get the 3-Pfister form $<< a, c, \lambda]]$ with the notations of [6], p. xxi.

6. TRIALITY FOR SEMILINEAR SIMILITUDES

Let $\mathfrak{C}$ be a Cayley algebra over F with conjugation $\pi : x \mapsto \overline{x}$ and norm $\mathfrak{n}\colon x \mapsto x\overline{x}$. The new multiplication $x \star y = \overline{x}\,\overline{y}$ satisfies

$$x \star (y \star x) = (x \star y) \star x = \mathfrak{n}(x) y \tag{6}$$

for x, $y \in \mathfrak{C}$. Further, the polar form $b_\mathfrak{n}$ is *associative* with respect to $\star$, in the sense that

$$b_\mathfrak{n}(x \star y, z) = b_\mathfrak{n}(x, y \star z).$$

PROPOSITION 6.1. *For x, $y \in \mathfrak{C}$, let $r_x(y) = y \star x$ and $\ell_x(y) = x \star y$. The map $\mathfrak{C} \to \operatorname{End}_F(\mathfrak{C} \oplus \mathfrak{C})$ given by*

$$x \mapsto \begin{pmatrix} 0 & \ell_x \\ r_x & 0 \end{pmatrix}$$

induces isomorphisms $\alpha\colon \big(C(\mathfrak{C}, \mathfrak{n}), \tau\big) \xrightarrow{\sim} \big(\operatorname{End}_F(\mathfrak{C} \oplus \mathfrak{C}), \sigma_{\mathfrak{n} \perp \mathfrak{n}}\big)$ and

$$\alpha_0\colon \big(C_0(\mathfrak{C}, \mathfrak{n}), \tau_0\big) \xrightarrow{\sim} \big(\operatorname{End}_F(\mathfrak{C}), \sigma_\mathfrak{n}\big) \times \big(\operatorname{End}_F(\mathfrak{C}), \sigma_\mathfrak{n}\big), \tag{7}$$

of algebras with involution.

Proof. We have $r_x\big(\ell_x(y)\big) = \ell_x\big(r_x(y)\big) = \mathfrak{n}(x) \cdot y$ by (6). Thus the existence of the map α follows from the universal property of the Clifford algebra. The fact that α is compatible with involutions is equivalent to

$$b_\mathfrak{n}\big(x \star (z \star y), u\big) = b_\mathfrak{n}\big(z, y \star (u \star x)\big)$$

for all x, y, z, u in $\mathfrak{C}$. This formula follows from the associativity of $b_{\mathfrak{n}}$. Since $C(\mathfrak{C},\mathfrak{n})$ is central simple, the map α is an isomorphism by a dimension count. □

Assume from now on that $\mathfrak{C}$ is defined over a field K which is quadratic Galois over F. Any proper semilinear similitude t of $\mathfrak{n}$ induces a semilinear automorphism $C(t)$ of the even Clifford algebra $\big(C_0(\mathfrak{C},\mathfrak{n}),\tau_0\big)$, which does not permute the two components of the center of $C_0(\mathfrak{C},\mathfrak{n})$. Thus $\alpha_0\circ C_0(t)\circ\alpha_0^{-1}$ is a pair of semilinear automorphisms of $\big(\mathrm{End}_K(\mathfrak{C}),\sigma_{\mathfrak{n}}\big)$. It follows as in (4.5) that, for any quadratic space (V,q), semilinear automorphisms of $(\mathrm{End}_K(V),\sigma_q,f_q)$ are of the form $\mathrm{Int}(f)$, where f is a semilinear similitude of q. The following result is due to Wonenburger [12] in characteristic different from 2:

Proposition 6.2. *For any proper semilinear similitude t_1 of $\mathfrak{n}$ with multiplier μ_1, there exist proper semilinear similitudes t_2, t_2 such that*

$$\alpha_0\circ C_0(t_1)\circ\alpha_0^{-1}=\big(\mathrm{Int}(t_2),\mathrm{Int}(t_3)\big)$$

and

$$\begin{aligned}\mu_3^{-1}t_3(x\star y)&=t_1(x)\star t_2(y),\\ \mu_1^{-1}t_1(x\star y)&=t_2(x)\star t_3(y),\\ \mu_2^{-1}t_2(x\star y)&=t_3(x)\star t_1(y).\end{aligned}\tag{8}$$

Let t_1 be an improper similitude with multiplier μ_1. There exist improper similitudes t_2, t_3 such that

$$\begin{aligned}\mu_3^{-1}t_3(x\star y)&=t_1(y)\star t_2(x),\\ \mu_1^{-1}t_1(x\star y)&=t_2(y)\star t_3(x),\\ \mu_2^{-1}t_2(x\star y)&=t_3(y)\star t_1(x).\end{aligned}$$

The pair (t_2,t_3) is determined by t_1 up to a factor (λ,λ^{-1}), $\lambda\in K^\times$, and we have $\mu_1\mu_2\mu_3=1$.
Furthermore, any of the formulas in (8) implies the two others.

Proof. The proof given in [6, (35.4)] for similitudes can also be used for semilinear similitudes. □

Remark 6.3. The class of two of the t_i, $i=1$, 2, 3, modulo $K^\times$ is uniquely determined by the class of the third t_i.

Corollary 6.4. *Let T_1 be a proper semilinear similitude of $(\mathfrak{C},\mathfrak{n})$ such that $T_1^2=\mu_1$, $\mu_1\in K^\times$ and with multiplier $-\mu_1$. There exist elements $a_i\in K^\times$, $i=1$, 2, 3, and proper semilinear similitudes T_i of $(\mathfrak{C},\mathfrak{n})$, with $T_i^2=\mu_i$, $\mu_i\in K^\times$ and with multiplier $-\mu_i$, $i=2$, 3, such that $a_i\overline{a_i}\mu_i=\mu_{i+1}\mu_{i+2}$ and*

$$\begin{aligned}a_3T_3(x\star y)&=T_1(x)\star T_2(y)\\ a_1T_1(x\star y)&=T_2(x)\star T_3(y)\\ a_2T_2(x\star y)&=T_3(x)\star T_1(y\end{aligned}$$

The class of any T_i modulo $K^\times$ determines the two other classes and the μ_i's are determined up to norms from $K^\times$. Furthermore any of the three formulas determines the two others.

Proof. Counting indices modulo 3, we have relations

$$T_i(x) \star T_{i+1}(y) = b_{i+2}T_{i+2}, \quad b_i \in K^\times$$

in view of (6.2). If we replace all T_j by $T_j \circ \rho_{\nu_j}$, $\nu_j \in K^\times$, we get new constants a_i. The claim then follows from (3.3). □

7. Triality for quadratic quaternion forms

Let $D_1 = K \oplus \ell_1 K = [K, \mu_1)$ be a quaternion algebra over F and let (V_1, q_{θ_1}) be a quaternion quadratic space of dimension 4 over D_1. Let $\theta_1 = [h_1]$, $h_1(x,y) = P_1(x,y) + \ell R_1(x,y)$, so that $[R_1] = \pi_2(\theta_1)$ corresponds to a 8-dimensional (classical) quadratic form on V_1^0 over K. The map $T_1 : V_1^0 \to V_1^0$, $T_1(x) = x\ell_1$, is a semilinear similitude of $\big(V_1^0, [R_1]\big)$ with multiplier $-\mu_1$ and such that $T_1^2 = \mu_1$. We recall that by (3.5) it is equivalent to have a quadratic quaternion space (V_1, q_{θ_1}) or a pair $\big(V_1^0, [T_1]\big)$. We assume from now on that the quadratic form $q_{[R_1]}$ is a 3-Pfister form, i.e.,the norm form $\mathfrak{n}$ of a Cayley algebra $\mathfrak{C}$ over K. In view of (6.4) T_1 induces two semilinear similitudes T_2, resp. T_3, with multipliers μ_2, resp. μ_3, which in turn define a quaternion quadratic space (V_2, θ_2) of dimension 4 over $D_2 = [K, \mu_2)$, resp. a quaternion quadratic space (V_3, θ_3) of dimension 4 over $D_3 = [K, \mu_3)$. Let $\operatorname{Br}(F)$ be the Brauer group of F.

Proposition 7.1. *1)* $[D_1][D_2][D_3] = 1 \in \operatorname{Br}(F)$,
2) The restriction of $\alpha : C_0\big(\mathfrak{C}, \mathfrak{n}\big) \xrightarrow{\sim} \operatorname{End}_K(\mathfrak{C}) \times \operatorname{End}_K(\mathfrak{C})$ *to* $C(V_i, D_i, \theta_i)$ *induces isomorphisms*

$$\alpha_i : \big(C(V_i, D_i, \theta_i), \tau\big) \xrightarrow{\sim} \big(\operatorname{End}_{D_{i+1}}(V_{i+1}), \sigma_{\theta_{i+1}}\big) \times \big(\operatorname{End}_{D_{i+2}}(V_{i+2}), \sigma_{\theta_{i+2}}\big)$$

Proof. The first claim follows from the fact that $\mu_1\mu_2 = \mu_3 \operatorname{Nrd}_{D_3}(a_3)$ and the second is a consequence of (5.5), (3.5) and the definition of α. □

Example 7.2. Let $\mathfrak{C}_0$ be a Cayley algebra over F and let $\mathfrak{C} = \mathfrak{C}_0 \otimes_F K$. For any $c \in \mathfrak{C}_0$ such that $c^2 = \mu_1 \in F^\times$, $T_1 : \mathfrak{C} \to \mathfrak{C}$ given by $T_1(k \otimes x) = \overline{k} \otimes xc$ is a semilinear similitude with multiplier $-\mu_1$ such that $T_1^2 = \mu_1$. The Moufang identity $(cx)(yc) = c(xy)c$ in $\mathfrak{C}$ implies that

$$(xc) \star (cy) = \overline{c}(x \star y)\overline{c}.$$

Thus $T_2(k \otimes y) = \overline{k} \otimes cy$ and $T_3(k \otimes z) = i\overline{k} \otimes \overline{c}z\overline{c}$ (where $i \in K^\times$ is such that $\overline{i} = -i$) satisfy (6.4). The corresponding triple of quaternion algebras is $\big([K, \mu_1), [K, \mu_1), [K, i\overline{i}\mu_1^2)\big)$, the third algebra being split.

Example 7.3. Let D_i, $i = 1, , 2, 3$, be quaternion algebras over F such that $[D_1][D_2][D_3] = 1 \in \operatorname{Br}(F)$. We may assume that the D_i contain a common separable quadratic field K and that $D_i = [K, \mu_i)$, $\mu_i \in F^\times$ such that $\mu_1\mu_2\mu_3 \in$

$F^{\times 2}$. In [6, (43.12)] similitudes S_i with multiplier μ_i, $i = 1, 2, 3$, of the split Cayley algebra $\mathfrak{C}_s$ over F are given, such that 1) $\mu_3^{-1} S_3(x \star y) = S_1(x) \star S_2(y)$ and 2) $S_i^2 = \mu_i$. Let $\mathfrak{C} = K \otimes \mathfrak{C}_s$. Let $u \in K^\times$ be such that $\overline{u} = -u$. The semilinear similitudes $T_i(k \otimes x) = u\overline{k} \otimes S_i(x)$, $i = 1, 2, 3$, satisfy

$$a_3 T_3(x \star y) = T_1(x) \star T_2(y)$$

with $a_3 = u\mu_3^{-1}$ (we use the same notation $\star$ in $\mathfrak{C}_s$ and in $\mathfrak{C}$). Thus there exist a triple of quadratic quaternion forms $(\theta_1, \theta_2, \theta_3)$ corresponding to the three given quaternion algebras. We hope to describe the corresponding quadratic quaternion forms in a subsequent paper.

References

[1] A. Bak. *K-Theory of forms*, volume 98 of *Annals of Mathematics Studies.* Princeton University Press, Princeton, N.J., 1981.

[2] E. Bayer-Fluckiger and R. Parimala. Galois cohomology of the classical groups over fields of cohomological dimension $\leq$ 2. *Invent. Math.*, 122(2):195–229, 1995.

[3] J. Dieudonné. Sur les groupes unitaires quaternioniques à deux ou trois variables. *Bull. Sci. Math.*, 77:195–213, 1953.

[4] M. A. Elomary. *Orthogonal sum of central simple algebras with quadratic pairs in characteristic* 2 *and classification theorems.* PhD thesis, Université Catholique de Louvain, 2000.

[5] M.-A. Knus. *Quadratic and Hermitian forms over rings*, volume 294 of *Grundlehren der Mathematischen Wissenschaften.* Springer-Verlag, Berlin, 1991. With a foreword by I. Bertuccioni.

[6] M.-A. Knus, A. A Merkurjev, M. Rost and J.-P. Tignol. *The Book of Involutions.* Number 44 in American Mathematical Society Colloquium Publications. American Mathematical Society, Providence, R.I., 1998.

[7] D. W. Lewis. New improved exact sequences of Witt groups. *J. Algebra*, 74:206–210, 1982.

[8] W. Scharlau. *Quadratic and Hermitian forms*, volume 270 of *Grundlehren der mathematischen Wissenschaften.* Springer-Verlag, Berlin, 1985.

[9] E. A. M. Seip-Hornix. Clifford algebras of quadratic quaternion forms. I, II. *Nederl. Akad. Wetensch. Proc. Ser. A 68 = Indag. Math.*, 27:326–363, 1965.

[10] J. Tits. Formes quadratiques, groupes orthogonaux et algèbres de Clifford. *Invent. Math.*, 5:19–41, 1968.

[11] C. T. C Wall. On the axiomatic foundations of the theory of Hermitian forms. *Proc. Camb. Phil. Soc.*, 67:243–250, 1970.

[12] M. J. Wonenburger. Triality principle for semisimilarities. *J. Algebra*, 1:335–341, 1964.

Max-Albert Knus
ETH Zentrum
CH-8092-Zürich
Switzerland
knus@math.ethz.ch

Oliver Villa
ETH Zentrum
CH-8092-Zürich
Switzerland